



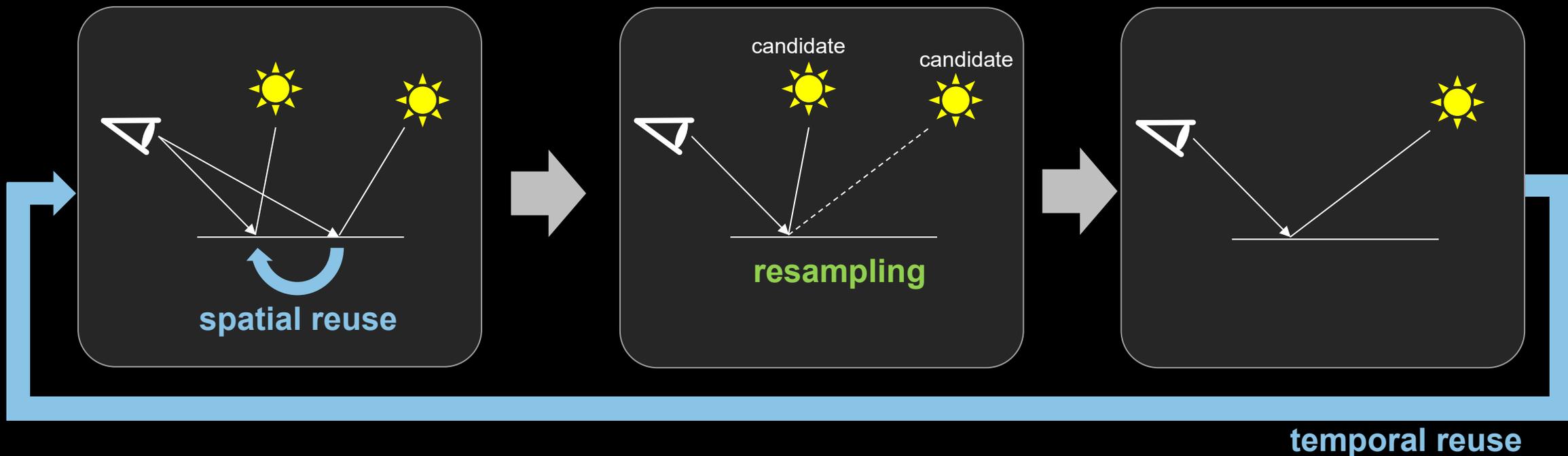
Efficient Visibility Reuse for Real-time ReSTIR

Yusuke Tokuyoshi



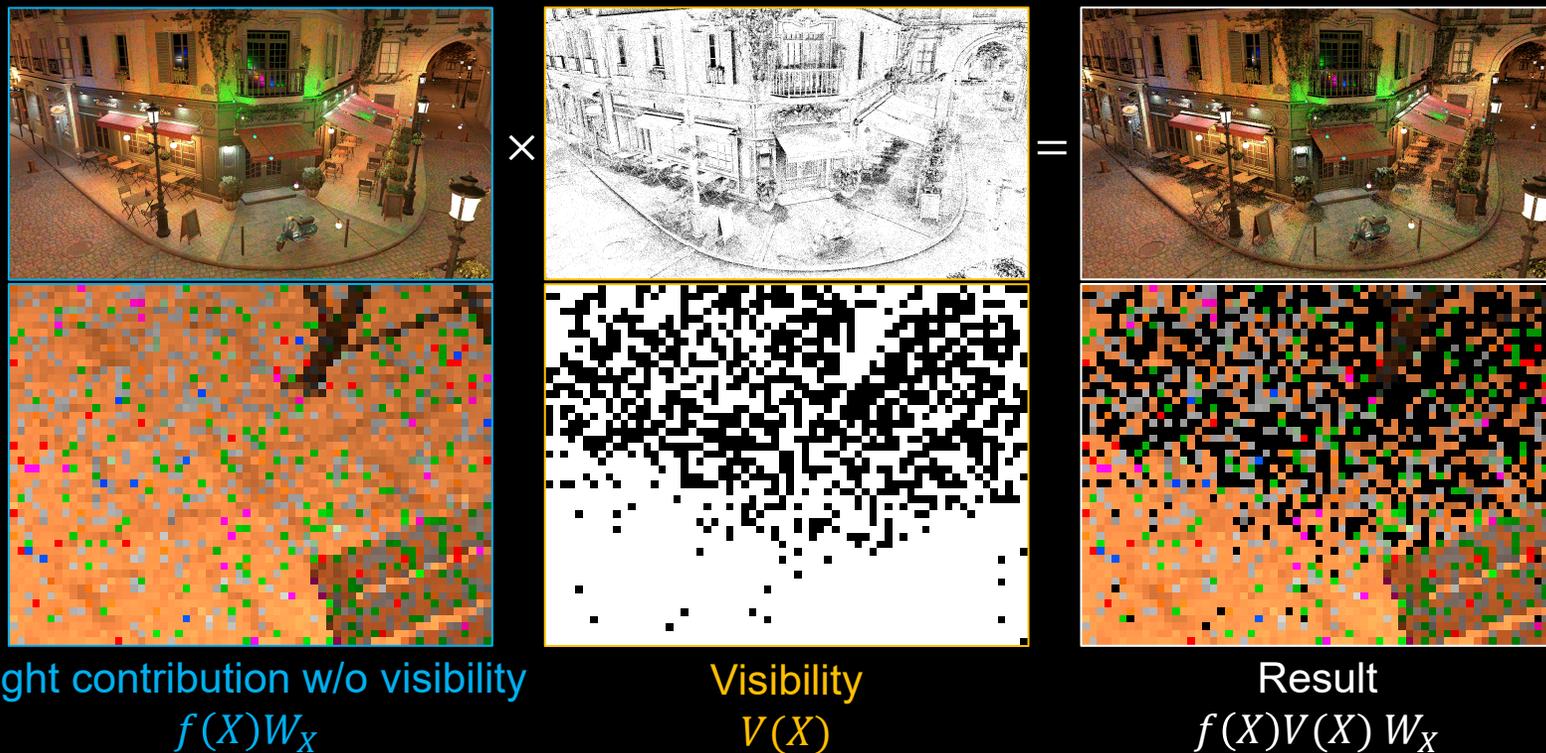
Spatiotemporal Reservoir Resampling (ReSTIR)

- Powerful importance resampling technique
- Reuse samples in **spatial neighbors** and **past frames** → many candidate samples ☺
- **Resample** according a target distribution \approx integrand (i.e., lighting with shadow rays)



Shadow Noise in Real-time ReSTIR [Bitterli et al. 2020; Wyman and Pantelev 2021]

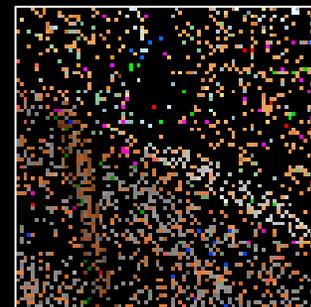
- Ignore shadow ray visibility for the target distribution
- Reduce the variance for the **light contribution** w/o shadow ray visibility 😊
- Inefficient to reduce **shadow noise** 😞



Reduce the shadow variance reusing visibilities

Previous Biased Visibility Reuse

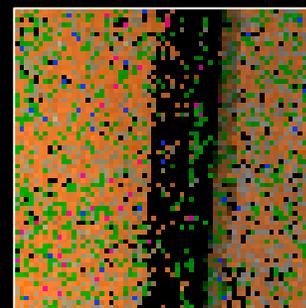
- Reuse the initial sample visibility [Bitterli et al. 2020]
 - Trace a shadow ray for the initial sample and reuse it for resampling weights
 - Significantly reduce the variance inside shadows ☺
 - Bias = darkening + temporal delay
 - Ineffective around shadow edges ☹
- Reuse the spatial sample visibility [Wyman and Panteleev 2021]
 - Trace a shadow ray for a (distant) spatial sample and reuse it for the integrand
 - Can control the shadow ray count (performance vs quality) ☺
 - Bias = temporal delay (+ shadow edge disappearance for small ray counts)
 - Does not reduce the shadow variance



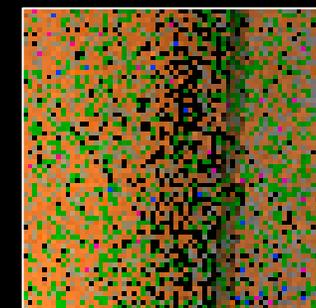
w/o vis. reuse



with vis. reuse



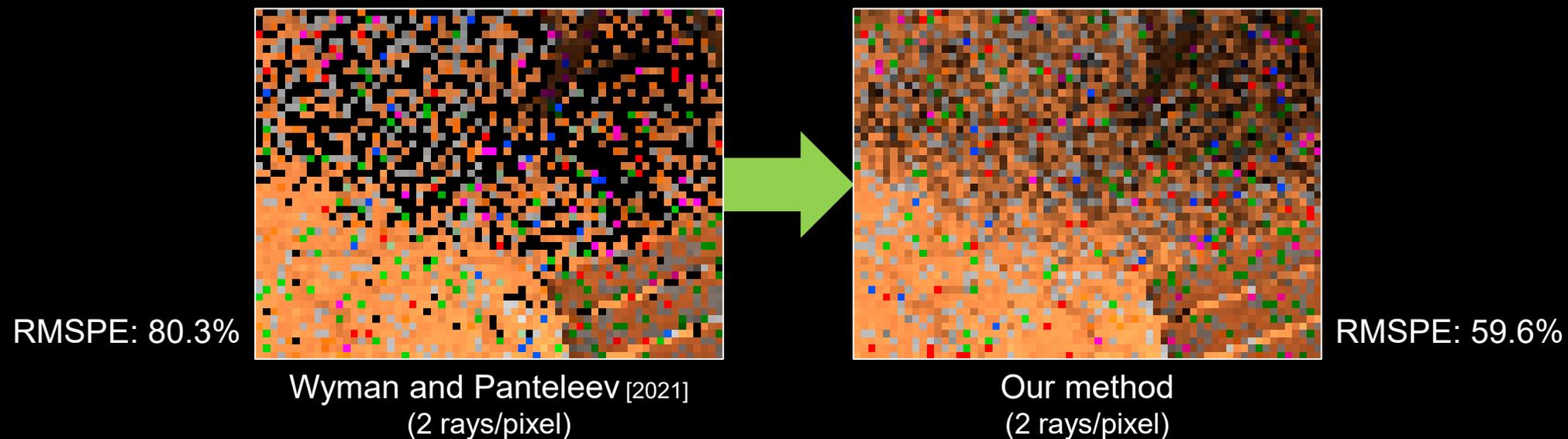
2 rays/pixel



1.25 rays/pixel

Our Method

- **Variance reduction method** based on Wyman and Panteleev's visibility reuse [2021]
 - Easy to implement 😊
- Additional bias for typical real-time implementations
- Discuss conditions to obtain unbiased results



Engine Tuning

- + Application/
 - [X] Display Frame Rate
 - [-] Display Profiler
- Experiments/
 - [X] Culling
 - Previous (2 rpp) ReSTIR
 - [-] Reference
- + Graphics/...
- + Renderer/...
- + Timing/...

Le Petit Coin



Previous method

Engine Tuning

- + Application/
 - [X] Display Frame Rate
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Le Petit Coin

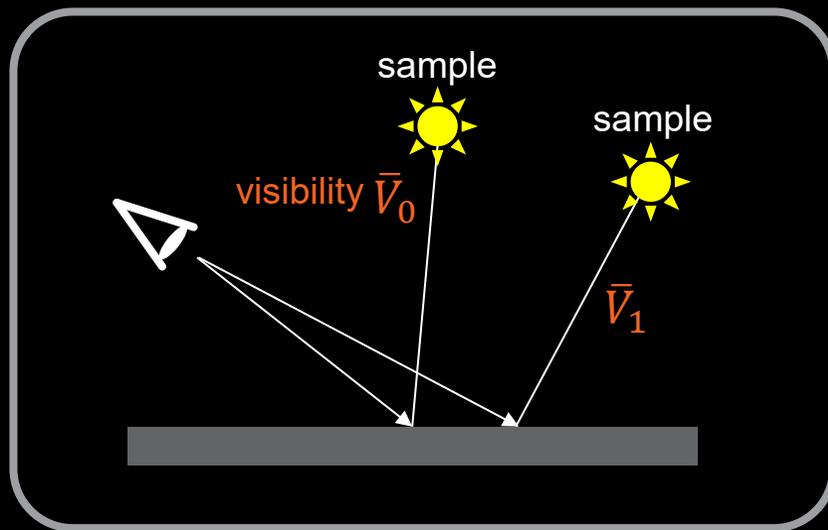


Our method

Our Method

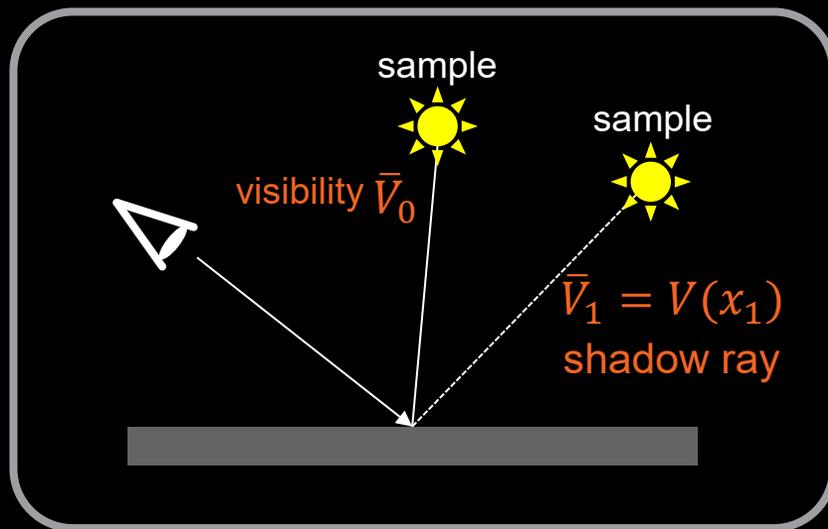
Our Visibility Reuse

- Reuse spatiotemporal sample visibilities for the integrand as in Wyman and Panteleev [2021]



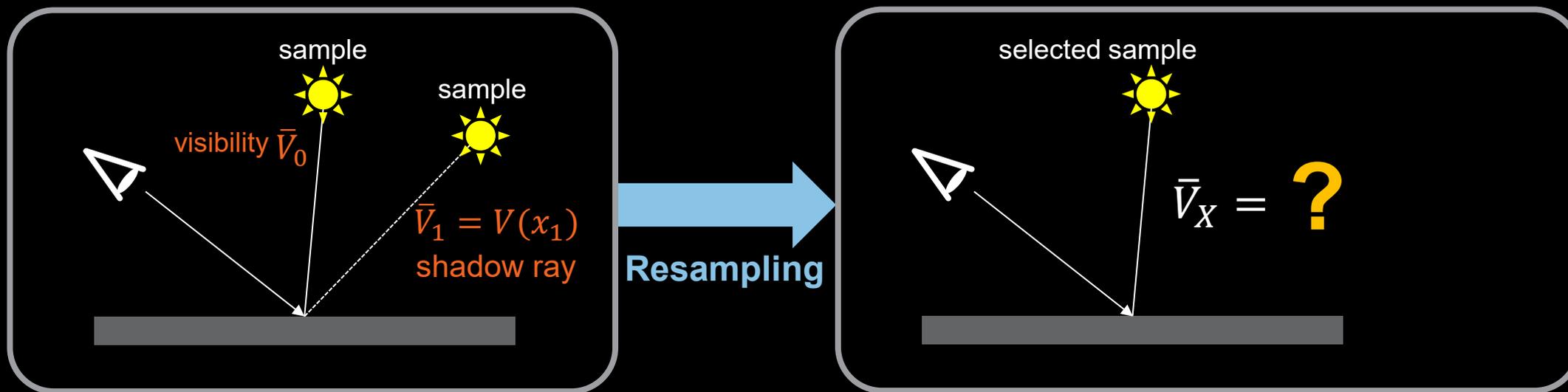
Our Visibility Reuse

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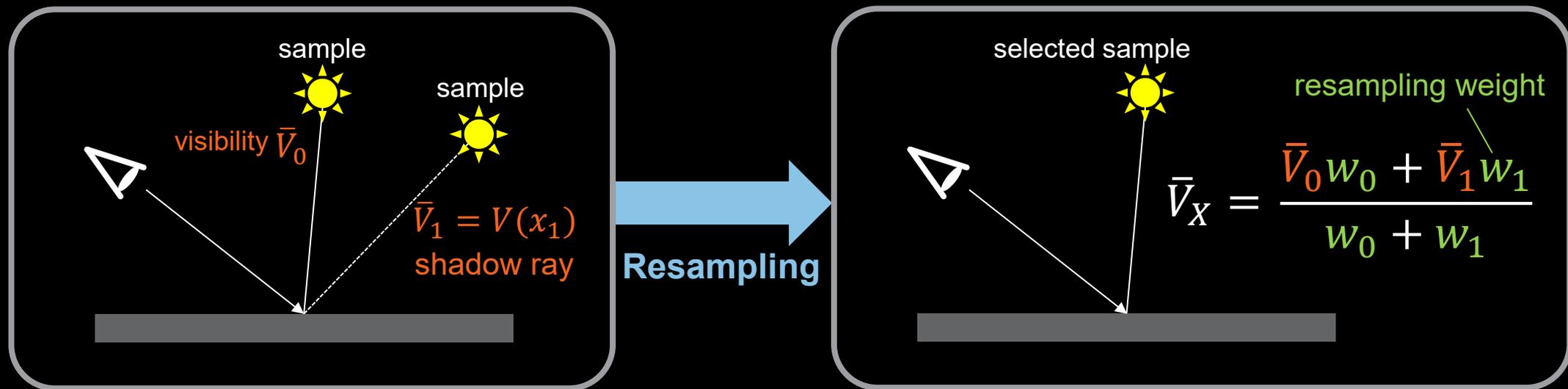
Our Visibility Reuse

- Reuse spatiotemporal sample visibilities for the integrand as in Wyman and Panteleev [2021]



Our Visibility Reuse

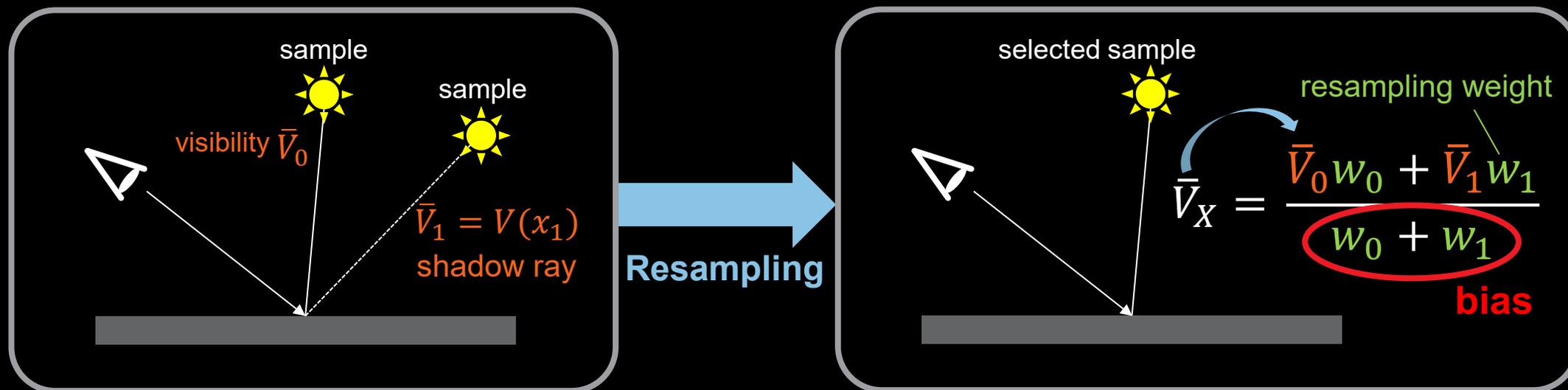
- Reuse spatiotemporal sample visibilities for the integrand as in Wyman and Panteleev [2021]
- Estimate a new visibility using a weighted average of visibilities unlike the previous method



Simple 😊

Our Visibility Reuse

- Reuse spatiotemporal sample visibilities for the integrand as in Wyman and Panteleev [2021]
- Estimate a new visibility using a weighted average of visibilities unlike the previous method
- A variant of *weighted importance sampling (WIS)* [Bekaert et al. 2000] (a.k.a. ratio estimator [Heitz et al. 2018])
 - Canonical sample visibility is also estimated by WIS in a chained manner
 - Biased estimator



Simple 😊

Bias Cancellation

- WIS is biased due to the **normalization**
- This **normalization is recursively cancelled** in ReSTIR ☺

$$\int_{\Omega} f(x)V(x)dx \approx f(X)\bar{V}_X W_X = f(X) \frac{\sum_i \bar{V}_i w_i}{\sum_i w_i} \frac{\sum_i w_i}{\hat{p}_c(X)} = \frac{f(X)}{\hat{p}_c(X)} \sum_i \bar{V}_i w_i$$

$$\bar{V}_i w_i = m_i(T_i(x_i)) \hat{p}_c(T_i(x_i)) \frac{\sum_k \bar{V}_k w_k}{\sum_k w_k} \frac{\sum_k w_k}{\hat{p}_i(x_i)} \left| \frac{\partial T_i}{\partial x_i} \right|$$

Remaining Two Biases

- Temporal shadow delay inherited from the previous method
 - In other words, $\sum_i \bar{V}_i w_i$ is unbiased for static shadows
- Ratio of the light contribution $f(X)$ and target distribution $\hat{p}_c(X)$
 - If this ratio is constant, we can avoid the bias

$$\int_{\Omega} f(x)V(x)dx \approx f(X)\bar{V}_X W_X = \frac{f(X)}{\hat{p}_c(X)} \sum_i \bar{V}_i w_i \approx \int_{\Omega} \hat{p}_c(x)V(x)dx$$

unbiased for static shadows

Biased correction term

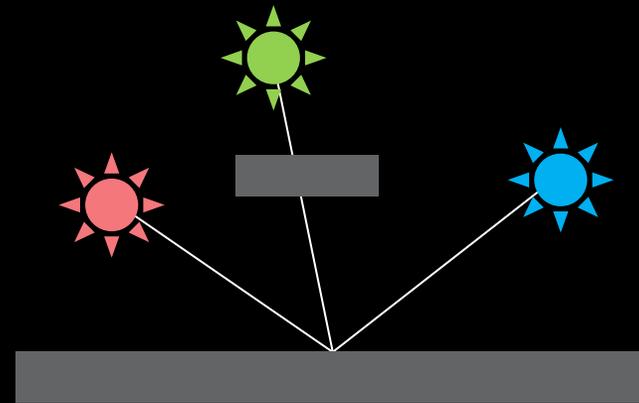
$$\int_{\Omega} \hat{p}_c(x)V(x)dx \rightarrow \int_{\Omega} f(x)V(x)dx$$

Using $\hat{p}_c(X) \propto f(X)$, our method is unbiased for static shadows

Avoid the Bias for Colored Light Sources?

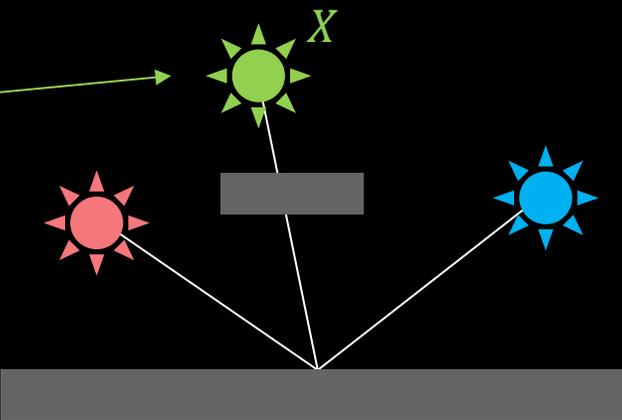
- The light contribution $f(X)$ can have different distributions between RGB channels
- Generate samples for each color channel?
- Randomly sample a color channel?

Expensive for real-time 😞



Biased Visibility Reuse for Real-time Rendering

- The light contribution $f(X)$ can have different distributions between RGB channels
- Approximate $\hat{p}_c(X)$ by the luminance of $f(X)$
- **Color of invisible lights can leak into shadows**, but it is still unbiased in luminance

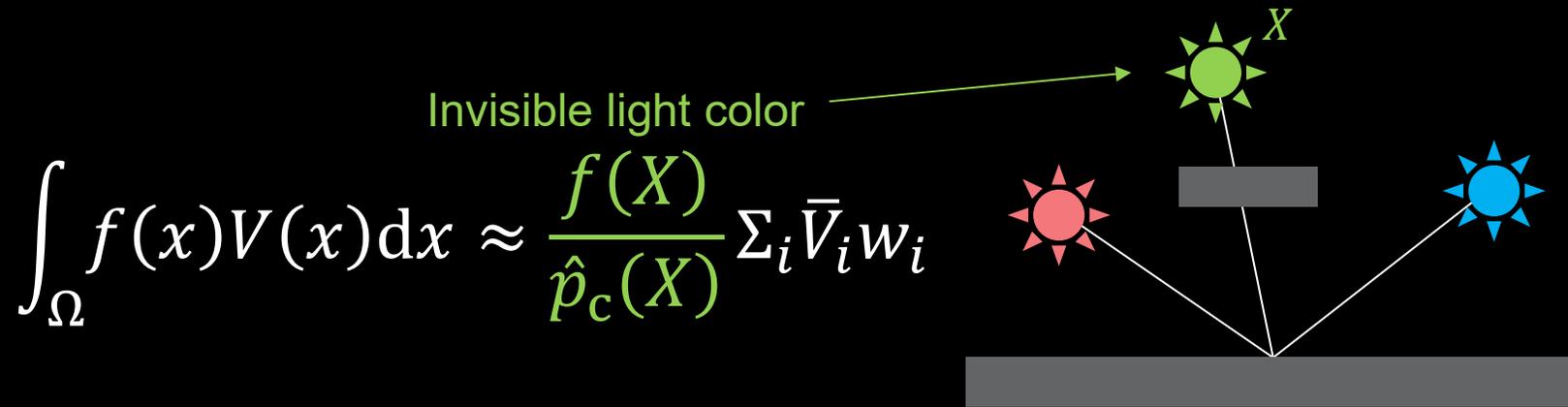
$$\int_{\Omega} f(x)V(x)dx \approx \frac{f(X)}{\hat{p}_c(X)} \sum_i \bar{V}_i w_i$$


Invisible light color

Invisible lights can be used as the correction term

Biased Visibility Reuse for Real-time Rendering

- The light contribution $f(X)$ can have different distributions between RGB channels
- Approximate $\hat{p}_c(X)$ by the luminance of $f(X)$
- **Color of invisible lights can leak into shadows**, but it is still unbiased in luminance
- Reduce this color leak bias by combining Bitterli et al.'s visibility reuse [2020]
 - Reduce the sampling of invisible lights



Biased Visibility Reuse for Real-time Rendering

- The light contribution $f(X)$ can have different distributions between RGB channels
- Approximate $\hat{p}_c(X)$ by the luminance of $f(X)$
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$$\int_{\Omega} f(x)V(x)dx \approx \frac{f(X)}{\hat{p}_c(X)} \sum_i \bar{V}_i w_i$$

visible light color

The diagram shows a grey surface with a point. Three suns are positioned above it: a red sun labeled 'X' is directly visible from the point. A green sun is behind a grey rectangular block, and a blue sun is behind a larger grey rectangular block. Lines connect each sun to the point on the surface, illustrating the visibility of each light source from that point.

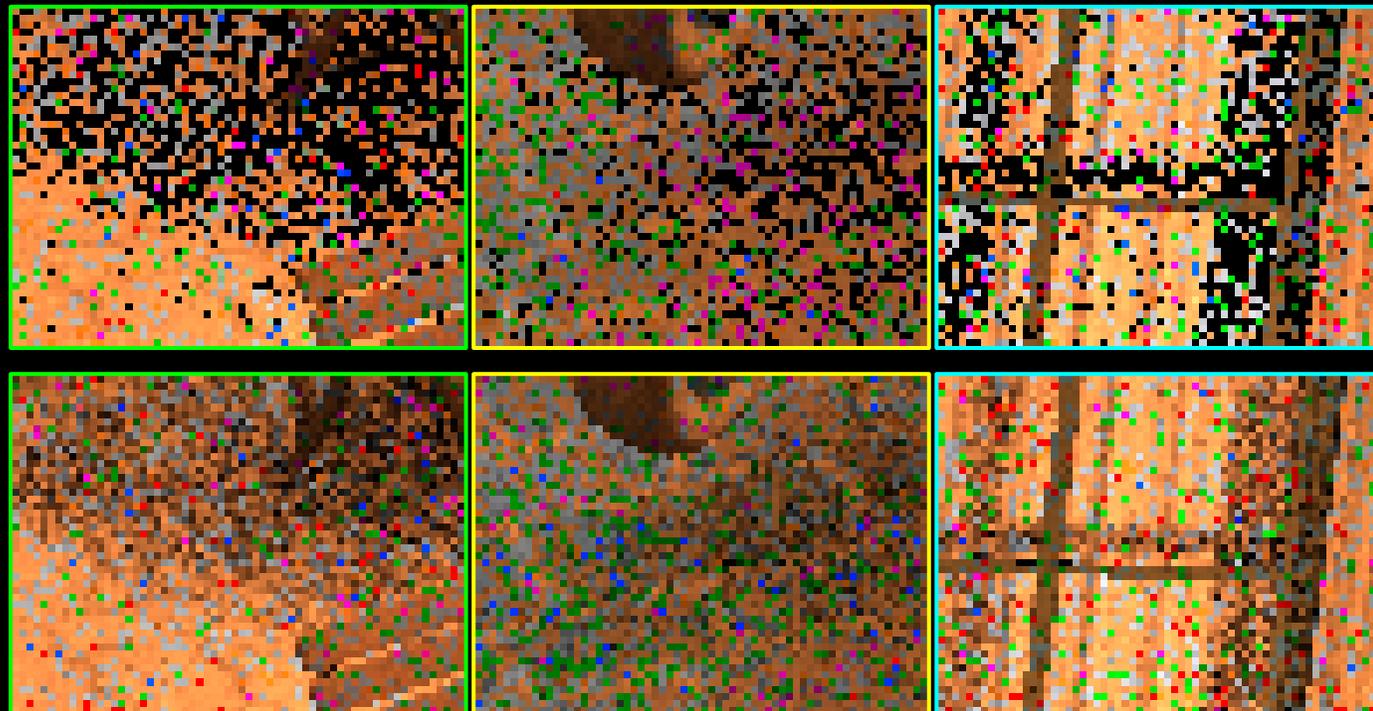
Results and Conclusion

Biased Visibility-Reuse ReSTIR, 2 rays/pixel

Previous method (7.85 ms, RMSPE: 80.3%)



1920×1080 pixels
AMD Radeon™ RX 7900 XTX GPU



Our method (7.86 ms, RMSPE: 59.6%)

Visualization of Visibility Term



×



=



×



=



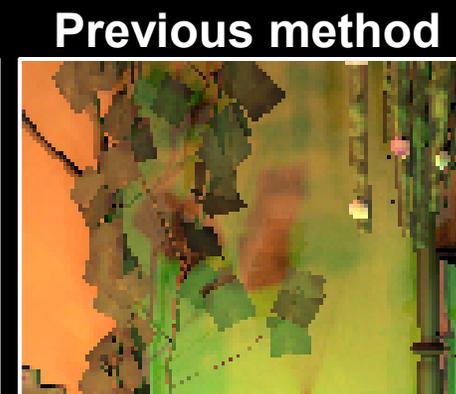
1920×1080 pixels
AMD Radeon™ RX 7900 XTX GPU

Our method

Indirect Illumination Using Virtual Point Lights [Keller 1997]



Limitation: Color Leak Bias



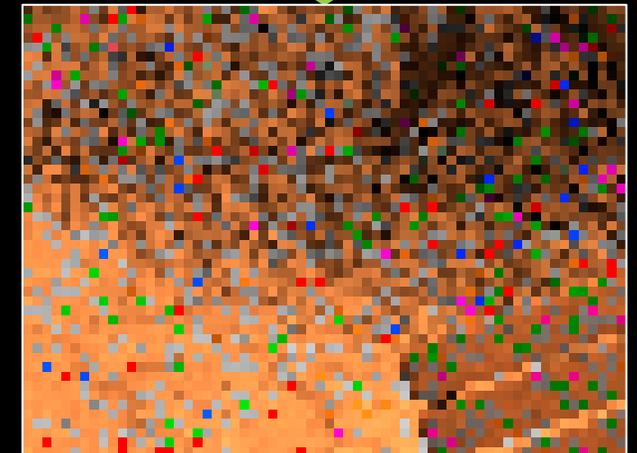
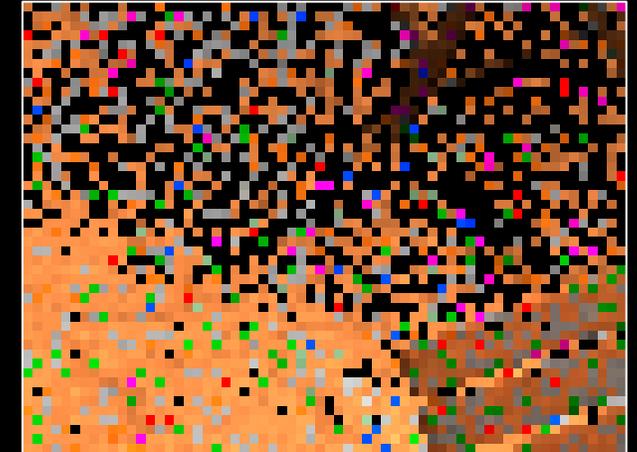
RMSPE: 15.3%
(darkening bias)

RMSPE: 15.7%
(darkening + color leak)

- Color leak bias for practical real-time rendering
 - Biased in color, but unbiased in luminance
- This additional color leak bias (+0.4%) is significantly smaller than Bitterli et al.'s darkening bias (15.3%)
- Can avoid the bias by generating samples for each RGB channel or sampling a color channel

Conclusion

- Variance reduction technique based on WIS for visibility-reuse ReSTIR
 - Bias due to WIS is recursively cancelled in ReSTIR
- Color leak bias can remain for colored lights
 - Can reduce this bias by combining Bitterli et al.'s visibility reuse
 - Also discussed conditions to obtain unbiased results
- Simple and efficient
 - Suitable for real-time rendering



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- Philippe Bekaert, Mateu Sbert, and Yves D. Willems. 2000. Weighted Importance Sampling Techniques for Monte Carlo Radiosity. In EGWR '00. 35–46.
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- Amazon Lumberyard. 2017. Amazon Lumberyard Bistro, Open Research Content Archive (ORCA).
- Chris Wyman and Alexey Panteleev. 2021. Rearchitecting Spatiotemporal Resampling for Production. In HPG '21.

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